Move Block

Moves two motors simultaneously

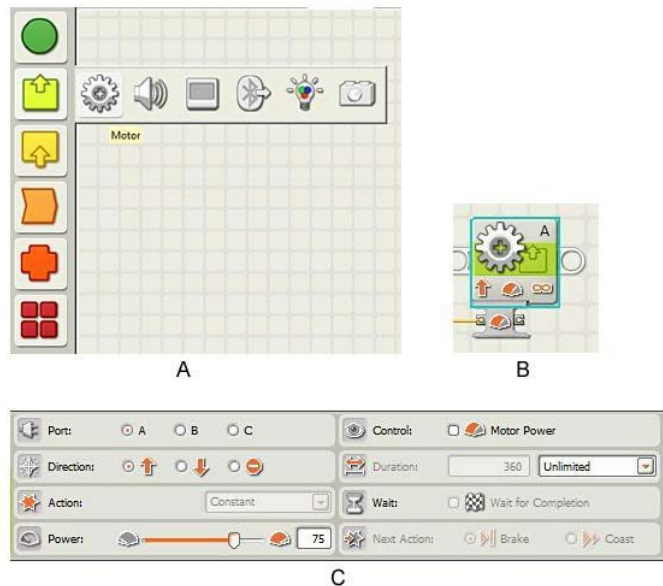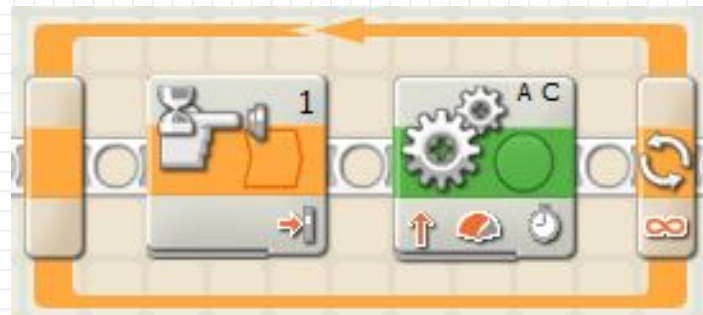*Degrees recommended movement duration

↑Power ↓Precision

Motor Block

A

B

C

Moves an individual motor

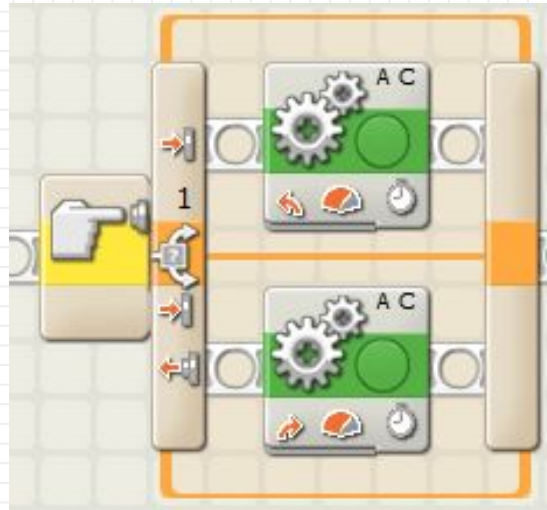Wait for Completion: Waits until movement is finished before running next block

Loop Block

Repetitively runs the blocks inside if a condition is met(forever, button push, etc)

This is where you use the sensor

Runs one chunk of blocks if a condition is met, otherwise it will run the other